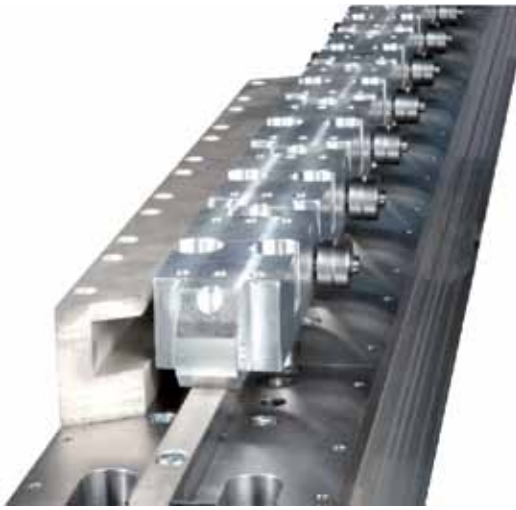


Precision Link Conveyor

LF Series



Precision Link Conveyor LF – design and mode of operation

The main component is a continuous chain manufactured from highly precise aluminum links. There are four cam followers per link for the vertical guidance and the guide rails are hardened and fine-milled. Two cam followers provide horizontal guidance through a hardened and milled guide rail. The links are connected by bolts and needle bearings.

The main frame is made from extruded aluminum and steel plates. The conveyor can be mounted to the extruded aluminum or the steel plates. Additional external stations can also be mounted there.

The chain is driven by a hardened cam wheel which is driven by a standard indexer or any other custom specified drive. At the other end, a hard 180° cam guides the chain. This cam is preloaded, so there is no backlash at the links. The linear stroke of the chain depends on the diameter of the cam wheel. One cycle of the indexer equals a linear stroke of one, two, or three links.

Advantages for design engineers and special machine builders

- Proven reliable through many years of service
- Vertical assembly - saves room. The empty carriers travel through the bottom of the machine
- Horizontal assembly - in an oval formation. Both sides of the machine can be used for assembly
- The alternative drive shaft of the indexer can be used for a synchronously rotating parallel shaft to drive other units
- The aluminum profile system can be used to mount other external stations fast and easily

Allowance for individual customer requirements

- Custom drives available
- Optional overload protection
- Dwell and index angle can be customized in a large range
- Non-standard links and linear strokes are possible
- The chain can be designed in metric or imperial units
- Customized color without additional cost
- Stainless steel, nickel plating or other special surfaces are available

Technical benefits for users

- High reliability and long lifetime
- Robust method of construction
- Proven to last many years
- Needle or ball bearings rolling in oil bath or on clean, dry and hard surfaces
- Low maintenance (only once a year check and adjust the pre-loading of the chain)
- Easy to operate using Allen Bradley PLC

The sky is the limit for the Motion product line. Flexible, made-to-order custom designs which are not featured in the product catalog have long been embedded in our corporate philosophy. We keep 10% of our entire workforce in reserve for these custom applications. Our skilled staff are available to assist our customers on a daily basis.

Our drives meet the highest standards regarding quality and precision. Our cams are manufactured in a different manner with regards to our competition, therefore it is often possible to use smaller rotary table sizes supplied by Motion instead of larger ones supplied by our competitors.

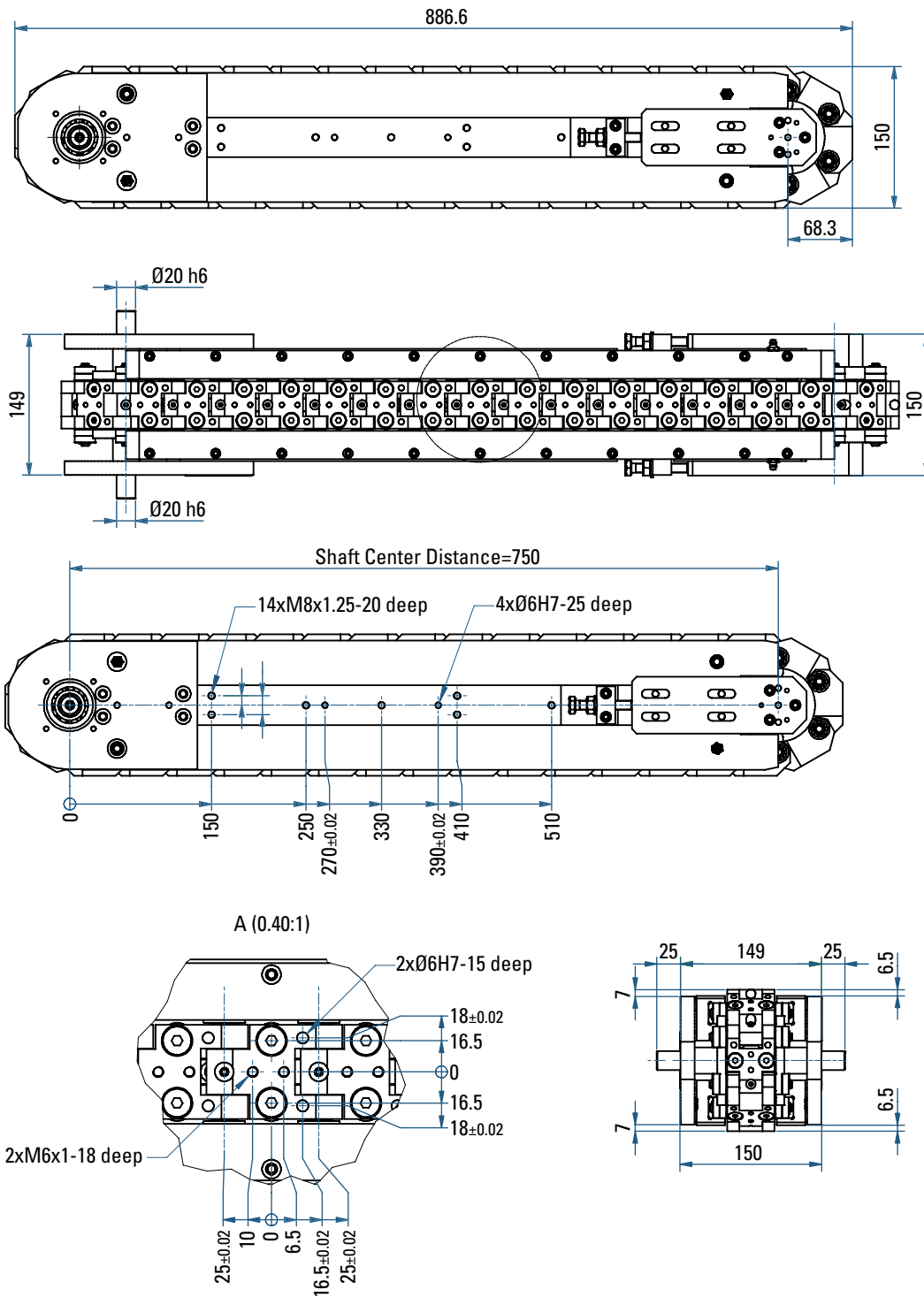
Our extensive design expertise enables us to meet customer requirements down to the last detail. We can combine the advantages of different forms of drives to create new value-added solutions which fit the bill completely. This is the added value which we have been offering to our customers in different sectors for many years.

Main fields

Assembly Industry, Medical Technology, Cosmetics, Electronic Industry

- Fast assembly of small parts - up to 150 cycles per minute
- Transportation and manufacturing of wires or similar parts
- Mechanical and optical investigation
- Welding, Tumbling, Riveting, Bending, Marking, Filling....

LF050



Dimensions

The dimensions pictured are standard for the LF050 Precision Link Conveyor. Customized applications centered around the LF050 standard size link can be manufactured upon request. Motion LF050 Conveyors can be mounted on the extruded aluminum. The links

and the steel plates can be machines to your specifications. The conveyor can be delivered without drive or the drive can be servo. Special dust covers or rubber lips between the links are available.

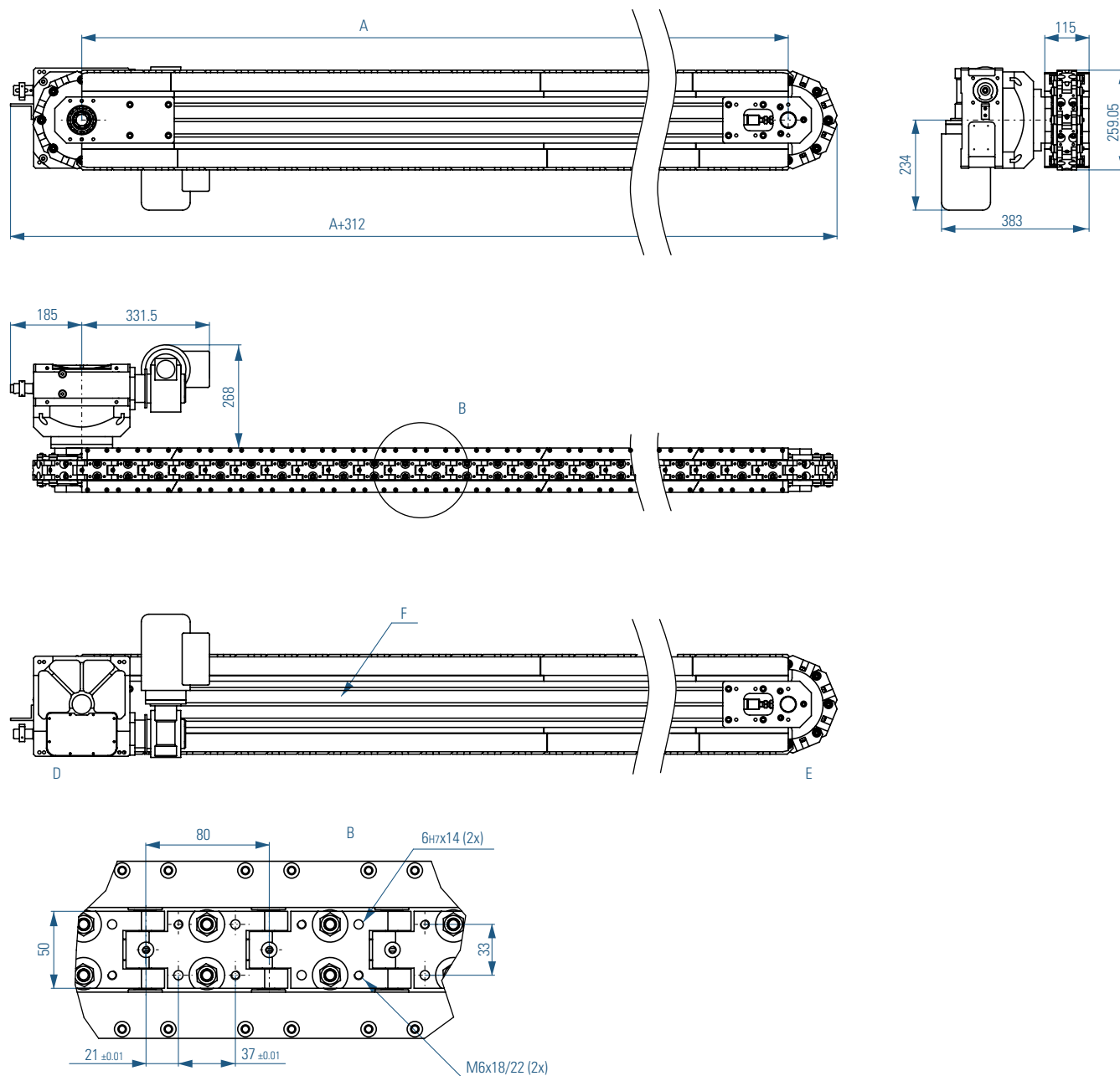
Load Table LF050

The load table for the LF050 is available only upon request at this time.

Technical specifications

Technical specifications for the LF050 are only available upon request at this time.

LF080



Dimensions

The dimensions shown here are the standard dimensions. Dimension "A" depends on the number of links. Motion LF080 Conveyors can be mounted on the extruded aluminum "F". The links and the steel plates can be machined to your specifications. The dimensions marked with * depend on the size of the drive used. The conveyor can be delivered without drive or the drive can be a servo. Special dust covers or rubber lips between the links are available.

The shown drive is a RT160 with brake motor (Kobold) size IEC71 and wormgear FRS50

⚠ Caution! Allow space on one side of the index wheel for adjusting the preload!

A = Distance Between U-Turns

D = Index Wheel

E = The 180° Cam

F = Aluminum Profile System 8-80x120

Load Table LF080

s [mm]	t [s]	$n_l = 12 ; n_r = 32$ A= 960mm				$n_l = 18 ; n_r = 44$ A= 1440mm				$n_l = 24 ; n_r = 56$ A= 1920mm				$n_l = 30 ; n_r = 68$ A= 2400mm				$n_l = 36 ; n_r = 80$ A= 2880mm			
		m [kg]				m [kg]				m [kg]				m [kg]				m [kg]			
		0.5	1	1.5	2	0.5	1	1.5	2	0.5	1	1.5	2	0.5	1	1.5	2	0.5	1	1.5	2
80 ¹⁾	t=	0.16	0.19	0.22	0.25	0.18	0.22	0.26	0.29	0.21	0.25	0.3	0.23	0.23	0.28	0.33	0.37	0.25	0.30	0.35	0.4
160 ²⁾	t=	0.24	0.29	0.34	0.38	0.28	0.34	0.40	0.45	0.31	0.39	0.45	0.35	0.35	0.43	0.50	0.56	0.38	0.46	0.54	0.61
240 ³⁾	t=	0.32	0.40	0.46	0.52	0.38	0.47	0.54	0.61	0.43	0.53	0.61	0.47	0.47	0.58	0.68	0.76	0.51	0.63	0.74	0.83

s [mm]	t [s]	$n_l = 42 ; n_r = 92$ A= 3360mm				$n_l = 48 ; n_r = 104$ A= 3840mm				$n_l = 54 ; n_r = 116$ A= 4320mm				$n_l = 60 ; n_r = 128$ A=4800mm				$n_l = 66 ; n_r = 140$ A=5280mm			
		m [kg]				m [kg]				m [kg]				m [kg]				m [kg]			
		0.5	1	1.5	2	0.5	1	1.5	2	0.5	1	1.5	2	0.5	1	1.5	2	0.5	1	1.5	2
80 ¹⁾	t=	0.27	0.33	0.38	0.43	0.28	0.35	0.41	0.46	0.60	0.37	0.43	0.49	0.31	0.39	0.45	0.51	0.33	0.41	0.48	0.54
160 ²⁾	t=	0.40	0.50	0.58	0.66	0.43	0.53	0.62	0.70	0.45	0.56	0.66	0.74	0.48	0.59	0.69	0.78	0.50	0.62	0.73	0.82
240 ³⁾	t=	0.55	0.68	0.79	0.90	0.59	0.73	0.85	0.96	0.62	0.77	0.90	1.01	0.65	0.81	0.95	1.07	0.68	0.85	0.99	1.12

s = Stroke [mm]
t = Stroke Time [s]

n_l = Number of links in line
 n_r = Number of links total

m = Weight per link [kg]
A = Distance between U-Turns

¹⁾ The chain moves one link with each index

²⁾ The chain moves two links with each index

³⁾ The chain moves three links with each index

Technical specifications

Main dimensions

Distance A** [mm]	in increments of 480
Weight at A=2000 [kg]	300
Stroke time** [s]	see Load Table
Stroke** [mm]	80, 160 or 240
Direction	right, left

Loadings

per static link	
Force vertical [N]	700
Force horizontal [N]	2600
Tilting moment [Nm]	80
Pull force at the chain [N]	750

Precision

in feed direction*	
at the drive [mm]	±0.04
opposite the drive [mm]	±0.07
Transverse to feed direction [mm]	±0.05
vertical runout [mm]	±0.03

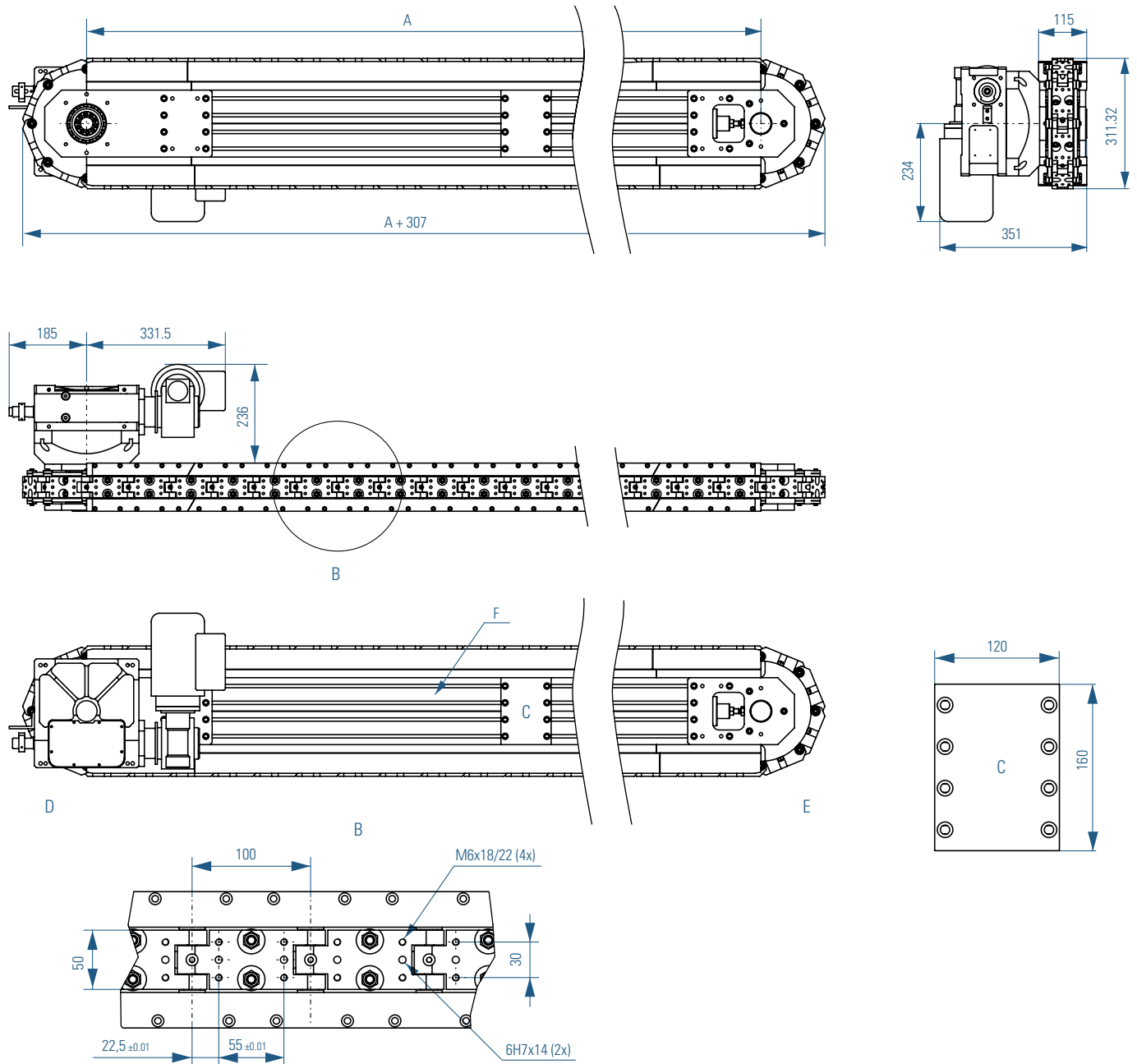
** Other distances "A", strokes or stroke times by request

Standard Drive

RT160 with 8¹, 4² or 8/3³ Indexes

* for the first and the last link in line we can not guarantee this precision.

LF100



Dimensions

The dimensions shown here are the standard dimensions. Dimension "A" depends on the number of links. Motion LF Conveyors can either be mounted on the extruded aluminum, "F" or on the steel plates "C". The links and the steel plates can be machined to your specifications. The dimensions

marked with * depend on the size of the drive used. The conveyor can be delivered without drive or the drive can be a servo. Special dust covers or rubber lips between the links are available.

The shown drive is a RT160 with brake motor (Kobold) size IEC71 and wormgear FRS50

⚠ Caution! Allow space on one side of the index wheel for adjusting the preload!

A = Distance Between U-Turns

D = Index Wheel

E = The 180° Cam

F = Aluminum Profile System 8-80x120

Load Table LF100

s [mm]	t [s]	$n_l = 10 ; n_r = 28$ A= 1000mm				$n_l = 15 ; n_r = 38$ A= 1500mm				$n_l = 20 ; n_r = 48$ A= 2000mm				$n_l = 25 ; n_r = 58$ A= 2500mm				$n_l = 30 ; n_r = 68$ A= 3000mm			
		m [kg]				m [kg]				m [kg]				m [kg]				m [kg]			
		0.5	1	1.5	2	0.5	1	1.5	2	0.5	1	1.5	2	0.5	1	1.5	2	0.5	1	1.5	2
100 ¹⁾	t=	0.16	0.19	0.22	0.24	0.18	0.22	0.26	0.29	0.21	0.25	0.29	0.32	0.23	0.28	0.32	0.36	0.25	0.30	0.34	0.39
200 ²⁾	t=	0.24	0.29	0.33	0.37	0.28	0.34	0.39	0.44	0.31	0.38	0.44	0.49	0.35	0.42	0.48	0.54	0.38	0.46	0.52	0.59
300 ³⁾	t=	0.33	0.40	0.46	0.51	0.38	0.46	0.53	0.60	0.43	0.52	0.60	0.67	0.47	0.57	0.66	0.74	0.51	0.62	0.72	0.80

s [mm]	t [s]	$n_l = 35 ; n_r = 78$ A= 3500mm				$n_l = 40 ; n_r = 88$ A= 4000mm				$n_l = 45 ; n_r = 98$ A= 4500mm				$n_l = 50 ; n_r = 108$ A=5000mm				$n_l = 55 ; n_r = 118$ A=5500mm			
		m [kg]				m [kg]				m [kg]				m [kg]				m [kg]			
		0.5	1	1.5	2	0.5	1	1.5	2	0.5	1	1.5	2	0.5	1	1.5	2	0.5	1	1.5	2
100 ¹⁾	t=	0.26	0.32	0.37	0.41	0.28	0.34	0.39	0.44	0.30	0.36	0.42	0.47	0.31	0.38	0.44	0.49	0.33	0.40	0.46	0.52
200 ²⁾	t=	0.40	0.49	0.56	0.63	0.43	0.52	0.60	0.67	0.45	0.55	0.63	0.71	0.47	0.58	0.67	0.75	0.50	0.60	0.70	0.79
300 ³⁾	t=	0.55	0.67	0.77	0.86	0.58	0.71	0.82	0.92	0.62	0.75	0.87	0.97	0.65	0.79	0.91	1.02	0.68	0.83	0.96	1.07

s = Stroke [mm]
t = Stroke Time [s]

n_l = Number of links in line
 n_r = Number of links total

m = Weight per link [kg]
A = Distance between U-Turns

¹⁾ The chain moves one link with each index

²⁾ The chain moves two links with each index

³⁾ The chain moves three links with each index

Technical specifications

Main dimensions

Distance A** [mm]	in increments of 500
Weight at A=2000 [kg]	350
Stroke time** [s]	see Load Table
Stroke** [mm]	100, 200 or 300
Direction	right, left

Loadings

per static link	
Force vertical [N]	700
Force horizontal [N]	2600
Tilting moment [Nm]	80
Pull force at the chain [N]	750

Precision

in feed direction*	
at the drive [mm]	±0.04
opposite the drive [mm]	±0.07
Transverse to feed direction [mm]	±0.05
vertical runout [mm]	±0.03

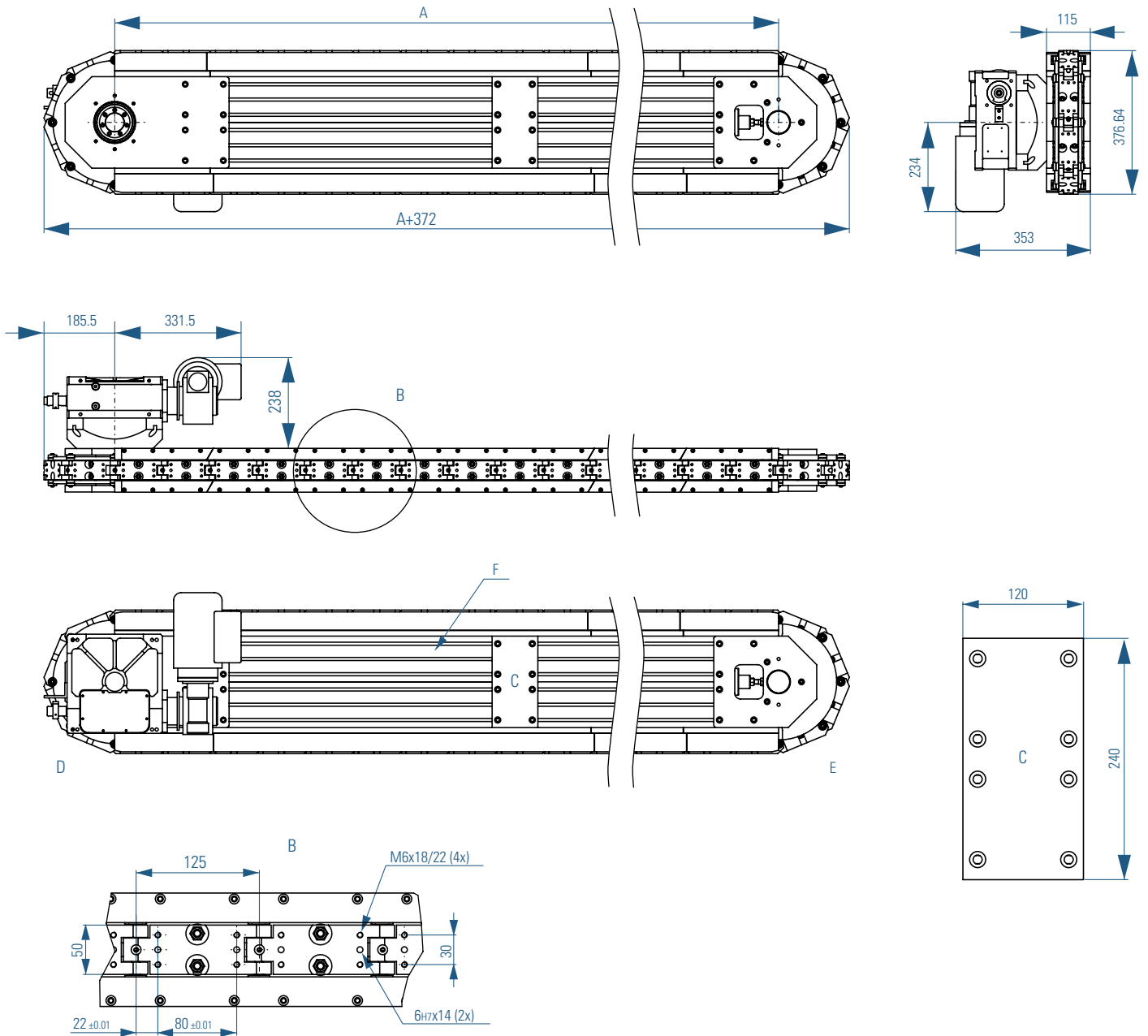
** Other distances "A", strokes or stroke times by request

Standard Drive

RT160 with 8¹, 4² or 8/3³ Indexes

* for the first and the last link in line we can not guarantee the precision.

LF125



The shown drive is a RT160 with brake motor (Kobold) size IEC71 and wormgear FRS50

Dimensions

The dimensions shown here are the standard dimensions. Dimension "A" depends on the number of links. Motion LF Conveyors can either be mounted on the extruded aluminum "F" or on the steel plates "C". The links and the steel plates can be machined to your specifications. The dimensions

marked with * depend on the size of the drive used. The conveyor can be delivered without drive or the drive can be a servo. Special dust covers or rubber lips between the links are available.

⚠ Caution! Allow space on one side of the index wheel for adjusting the preload!

A = Distance Between U-Turns

D = Index Wheel

E = The 180° Cam

F = Aluminum Profile System 8-80x120

Load Table LF125

s [mm]	t [s]	$n_l = 8 ; n_r = 24$ A= 1000mm				$n_l = 12 ; n_r = 32$ A= 1500mm				$n_l = 16 ; n_r = 40$ A= 2000mm				$n_l = 20 ; n_r = 48$ A= 2500mm				$n_l = 24 ; n_r = 56$ A= 3000mm			
		m [kg]				m [kg]				m [kg]				m [kg]				m [kg]			
		0.5	1	1.5	2	0.5	1	1.5	2	0.5	1	1.5	2	0.5	1	1.5	2	0.5	1	1.5	2
125 ¹⁾	t=	0.17	0.20	0.23	0.25	0.19	0.23	0.26	0.29	0.22	0.26	0.29	0.32	0.24	0.28	0.32	0.36	0.26	0.30	0.35	0.39
250 ²⁾	t=	0.25	0.30	0.34	0.38	0.29	0.35	0.40	0.44	0.33	0.39	0.45	0.49	0.36	0.43	0.49	0.54	0.39	0.46	0.53	0.59
375 ³⁾	t=	0.35	0.41	0.47	0.52	0.40	0.48	0.54	0.60	0.45	0.53	0.61	0.68	0.49	0.59	0.67	0.74	0.53	0.63	0.72	0.80

s [mm]	t [s]	$n_l = 28 ; n_r = 64$ A= 3500mm				$n_l = 32 ; n_r = 72$ A= 4000mm				$n_l = 36 ; n_r = 80$ A= 4500mm				$n_l = 40 ; n_r = 88$ A=5000mm				$n_l = 44 ; n_r = 96$ A=5500mm			
		m [kg]				m [kg]				m [kg]				m [kg]				m [kg]			
		0.5	1	1.5	2	0.5	1	1.5	2	0.5	1	1.5	2	0.5	1	1.5	2	0.5	1	1.5	2
125 ¹⁾	t=	0.27	0.33	0.37	0.41	0.29	0.35	0.40	0.44	0.31	0.37	0.42	0.46	0.32	0.38	0.44	0.49	0.34	0.40	0.46	0.51
250 ²⁾	t=	0.42	0.50	0.57	0.63	0.44	0.53	0.60	0.67	0.47	0.56	0.64	0.71	0.49	0.58	0.67	0.74	0.51	0.61	0.70	0.78
375 ³⁾	t=	0.57	0.68	0.77	0.86	0.60	0.72	0.82	0.92	0.64	0.76	0.87	0.97	0.67	0.80	0.91	1.02	0.70	0.83	0.95	1.06

s = Stroke [mm]
t = Stroke Time [s]

n_l = Number of links in line
 n_r = Number of links total

m = Weight per link [kg]
A = Distance between U-Turns

¹⁾ The chain moves one link with each index

²⁾ The chain moves two links with each index

³⁾ The chain moves three links with each index

Technical specifications

Main dimensions

Distance A** [mm]	in increments of 500
Weight at A=2000 [kg]	400
Stroke time** [s]	see Load Table
Stroke** [mm]	125, 250 or 375
Direction	right, left

Loadings

per static link	
Force vertical [N]	700
Force horizontal [N]	2600
Tilting moment [Nm]	80
Pull force at the chain [N]	750

Precision

in feed direction*	
at the drive [mm]	±0.04
opposite the drive [mm]	±0.07
Transverse to feed direction [mm]	±0.05
vertical runout [mm]	±0.03

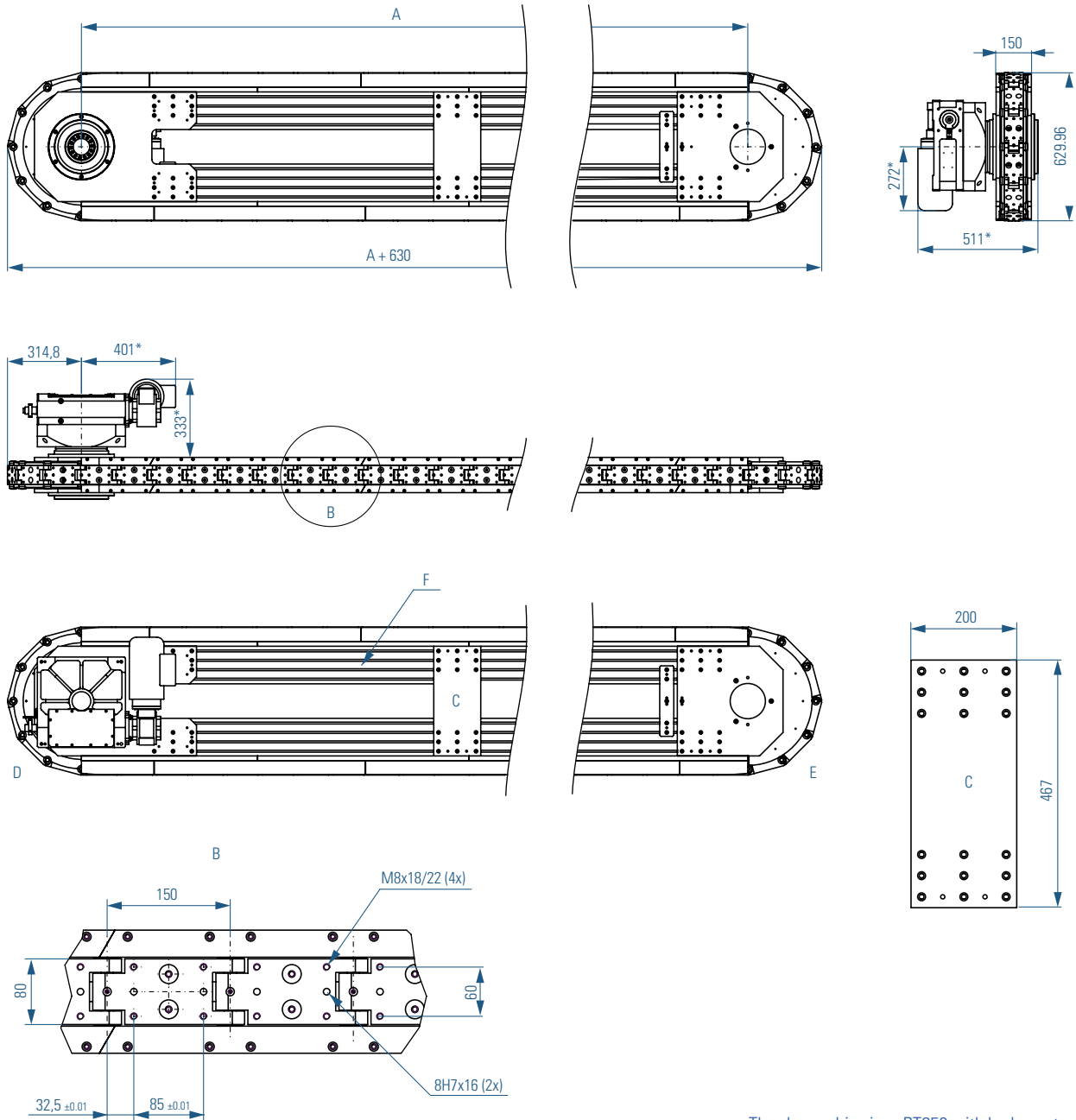
** Other distances "A", strokes or stroke times by request

Standard Drive

RT160 with 8¹, 4² or 8/3³ Indexes

* for the first and the last link in line we can not guarantee the precision.

LF150



Dimensions

The dimensions shown here are the standard dimensions. Dimension "A" depends on the number of links. Motion LF Conveyors can either be mounted on the extruded aluminum "F" or on the steel plates "C". The links and the steel plates can be machined to your specifications. The dimensions

marked with * depend on the size of the drive used. The conveyor can be delivered without drive or the drive can be a servo. Special dust covers or rubber lips between the links are available.

The shown drive is a RT250 with brake motor (Kobold) size IEC80 and wormgear FRS60

⚠ Caution! Allow space on one side of the index wheel for adjusting the preload!

A = Distance Between U-Turns

D = Index Wheel

E = The 180° Cam

F = Aluminum Profile System 8-80x120

Load Table LF150

s [mm]	t [s]	$n_l = 8 ; n_r = 28$ A= 1200mm				$n_l = 12 ; n_r = 36$ A= 1800mm				$n_l = 16 ; n_r = 44$ A= 2400mm				$n_l = 20 ; n_r = 52$ A= 3000mm				$n_l = 24 ; n_r = 60$ A= 3600mm			
		m [kg]				m [kg]				m [kg]				m [kg]				m [kg]			
		0.5	1	1.5	2	0.5	1	1.5	2	0.5	1	1.5	2	0.5	1	1.5	2	0.5	1	1.5	2
150 ¹⁾	t=	0.28	0.30	0.32	0.34	0.30	0.33	0.35	0.38	0.32	0.35	0.38	0.41	0.34	0.37	0.40	0.44	0.35	0.39	0.43	0.46
300 ²⁾	t=	0.39	0.42	0.46	0.48	0.42	0.46	0.50	0.53	0.45	0.49	0.54	0.57	0.48	0.53	0.57	0.62	0.50	0.56	0.61	0.65
450 ³⁾	t=	0.52	0.56	0.60	0.64	0.56	0.61	0.66	0.70	0.59	0.65	0.71	0.76	0.63	0.69	0.75	0.81	0.66	0.73	0.80	0.86

s [mm]	t [s]	$n_l = 28 ; n_r = 68$ A= 4200mm				$n_l = 32 ; n_r = 76$ A= 4800mm				$n_l = 36 ; n_r = 84$ A= 5400mm				$n_l = 40 ; n_r = 92$ A=6000mm				$n_l = 44 ; n_r = 100$ A=6600mm			
		m [kg]				m [kg]				m [kg]				m [kg]				m [kg]			
		0.5	1	1.5	2	0.5	1	1.5	2	0.5	1	1.5	2	0.5	1	1.5	2	0.5	1	1.5	2
150 ¹⁾	t=	0.37	0.41	0.45	0.49	0.39	0.43	0.47	0.51	0.40	0.45	0.50	0.54	0.42	0.47	0.52	0.56	0.43	0.49	0.54	0.58
300 ²⁾	t=	0.52	0.58	0.64	0.69	0.55	0.61	0.67	0.73	0.57	0.64	0.70	0.76	0.59	0.66	0.73	0.79	0.61	0.69	0.76	0.82
450 ³⁾	t=	0.69	0.77	0.84	0.91	0.72	0.81	0.88	0.96	0.75	0.84	0.92	1.00	0.78	0.87	0.96	1.04	0.81	0.91	1.00	1.09

s = Stroke [mm]
t = Stroke Time [s]

n_l = Number of links in line
 n_r = Number of links total

m = Weight per link [kg]
A = Distance between U-Turns

¹⁾ The chain moves one link with each index

²⁾ The chain moves two links with each index

³⁾ The chain moves three links with each index

Technical specifications

Main dimensions

Distance A** [mm]	in increments of 600
Weight at A=2000 [kg]	800
Stroke time** [s]	see Load Table
Stroke** [mm]	150, 300 or 450
Direction	right, left

Loadings

per static link	
Force vertical [N]	1250
Force horizontal [N]	2600
Tilting moment [Nm]	120
Pull force at the chain [N]	900

Precision

in feed direction*	
at the drive [mm]	±0.04
opposite the drive [mm]	±0.07
Transverse to feed direction [mm]	±0.05
vertical runout [mm]	±0.03

** Other distances "A", strokes or stroke times by request

Standard Drive

RT160 with 8¹, 4² or 8/3³ Indexes

* for the first and the last link in line we can not guarantee the precision.

Inquiry and order form for Motion LF conveyor



Company _____

Email Address _____

Contact person _____

Project no. / Order no. _____

Tel. / Fax _____

Date _____

Type

- LF080
- LF100
- LF125
- LF150
- other type _____

Distance A [mm] _____

Number of links in line n_l _____

Stroke (1 x, 2 x or 3 x length of one link) _____

- vertical assembly (using links on top)
- horizontal assembly (using links on both sides)

Mode of motion

- Stop mode (Fixed index time, Variable dwell time)
index time _____
- Continuous mode (Fixed index and dwell time)
Number of cycles per minute _____
Ratio index time : dwell time (or angle) _____

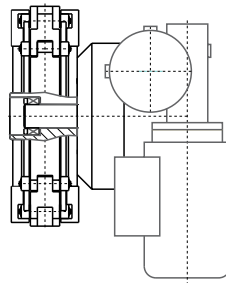
Payload

Weight of tooling _____

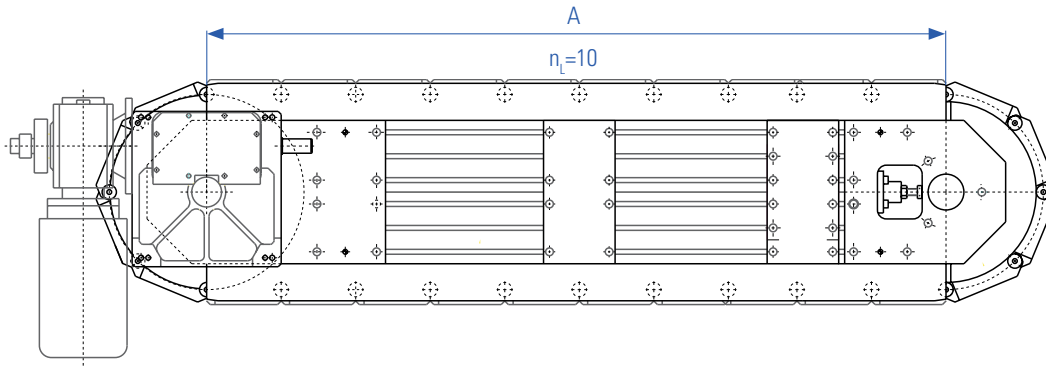
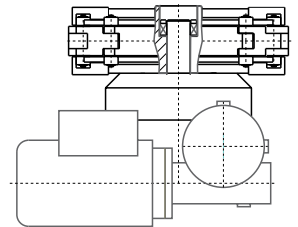
Weight of tooling _____

Distance from center point of mass of payload
to surface of the link _____

vertical assembly



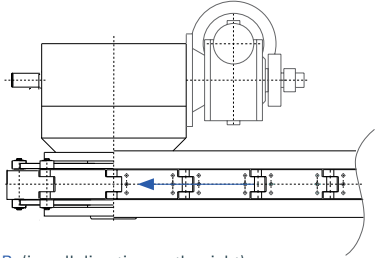
horizontal assembly



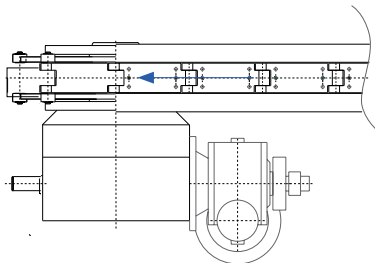


Inquiry and order form for Motion LF conveyor

Possible mounting positions for the drive units

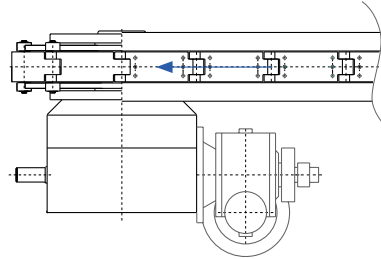


R (in pull direction on the right)

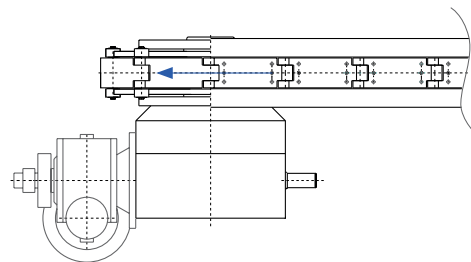


L (in pull direction on the left)

Position of the free drive shaft



A (drive shaft to the outside)



I (drive shaft to the inside)

Drive

With indexer

Mounting position of drive L R

Position of the free drive shaft A I

Motor voltage 277/480V 60Hz

230/400V 50Hz

other _____

Brake Voltage 24V DC

230V AC

400V AC

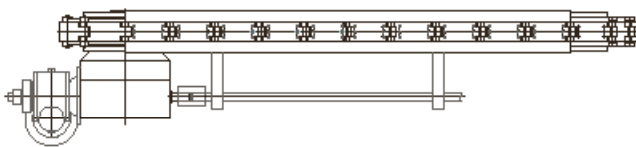
other _____

Safety clutch at the drive yes no

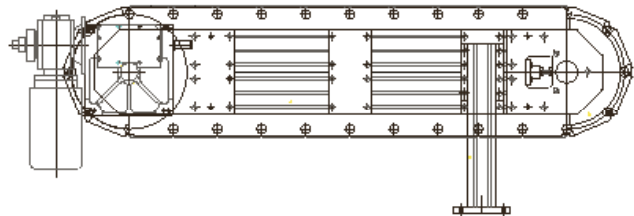
Without drive

With custom specified drive _____

Accessories



Synchronously running shaft - drawing #: _____



Machine feet (only at vertical assembly)

Number _____

Distance between floor and upper link _____

Allen Bradley PLC

Allen Bradley PLC Yes No